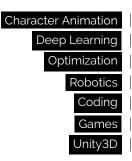




ABOUT

Sebastian Starke is a Research Scientist at Meta Reality Labs, working on character animation and artificial intelligence for virtual avatars. Before that, he worked as Sr. Al Scientist at Electronic Arts and interned twice at Adobe Research. Sebastian received a Ph.D. in Animation from the University of Edinburgh and a Dr. rer. nat. in Robotics from the University of Hamburg, where he also completed his M.Sc. and B.Sc. in Informatics. Sebastian is passionate about state-of-the-art technology in games, films and animation, and constantly focuses on advancing research in computer graphics using artificial intelligence.

EXPERTISE



REFERENCES

Taku Komura, Professor, UoE Jensen Huang, CEO, NVIDIA Danny Lange, SVP, Unity Jovan Popovic, VP, Adobe Systems Claire Delaunay, VP, NVIDIA Mohsen Sardari, Head of ML, Block Kazi Zaman, CDO, Shoreline

EXPERIENCE

2022/6 – now Research Scientist Meta, London, UK

Research on VR-based character control tasks.

2021/11 - 2022/6 Senior Al Scientist Electronic Arts, Redwood City, USA

Research on data-driven character control and motion matching (see SIGGRAPH 2022 paper).

2020/2 - 2021/11 Al Scientist Electronic Arts, Redwood City, USA

Research on neural animation layering (see SIGGRAPH 2021 paper), enhancement of motion

matching systems and motion style transfer.

2019/8 – 2020/2 Al Scientist Intern Electronic Arts, Redwood City, USA

Research on local motion phases for basketball plays (see SIGGRAPH 2020 paper).

2019/2 - 2019/6 Creative Intelligence Intern Adobe Research, Edinburgh, UK

Research on character-scene interactions and quadrupedal motion control in VR applications.

2018/10 - 2019/2 Lecturer University of Edinburgh, UK

Teaching the Computer Graphics and Visualization course.

2018/6 - 2018/9 Creative Intelligence Intern Adobe Research, Seattle, USA

Research on data-driven character-scene interactions (see SIGGRAPH Asia 2019 paper).

2017/10 - 2018/1 Tutor University of Edinburgh, UK

Tutoring the Computer Graphics and Visualization assignments.

2016/6 – 2017/8 Research Associate University of Hamburg, GER

Research on dexterous manipulation and full-body inverse kinematics (see IROS/ICRA papers).

2014/9 - 2016/6 Student Associate University of Hamburg, GER

Research on person detection and tracking with RGB-D cameras.

EDUCATION

2017 – 2022 Ph.D. in Animation University of Edinburgh, UK

Deep Learning for Character Animation and Control

2016 – 2020 Dr. rer. nat. in Robotics University of Hamburg, GER

BioIK: A Memetic Evolutionary Algorithm for Multi-Objective Inverse Kinematics

2014 – 2016	M.Sc. in Informatics Specialization in Robotics, Computer Vision and Bio-Inspired Al	University of Hamburg, GER
2009 - 2014	B.Sc. in Informatics Specialization in 3D Graphics/Geometry and Game Programming	University of Hamburg, GER

2022	Door Dhoos, Daviadia Automandaya fay Laawiyay Matiay Dhoos Mayifa
2022	Avatars Grow Legs: Generating Smooth Human Motion from Sparse T fusion Model Yuming Du, Robin Kips, Albert Pumarola, Sebastian Starke, Ali Thabet, A
PUBLICATIONS	

2022	Avatars Grow Legs: Generating Smooth Human Motion from Sparse Tracking Inputs with Diffusion Model Yuming Du, Robin Kips, Albert Pumarola, Sebastian Starke, Ali Thabet, Artsiom Sanakoyeu
2022	DeepPhase: Periodic Autoencoders for Learning Motion Phase Manifolds ACM SIGGRAPH / ТОВ Sebastian Starke, lan Mason, Taku Komura
2022	Learning Soccer Juggling Skills with Layer-wise Mixture-of-Experts Zhaoming Xie, Sebastian Starke, Hung Yu Ling, Michiel van de Panne
2022	COUCH: Towards Controllable Human-Chair Interactions Xiaohan Zhang, Bharat Lal Bhatnagar, Vladimir Guzov, Sebastian Starke , Gerard Pons-Moll
2021	Real-Time Style Modelling of Human Locomotion via Feature-Wise Transformations and Local Motion Phases Ian Mason, Sebastian Starke, Taku Komura
2021	Neural Animation Layering for Synthesizing Martial Arts Movements Sebastian Starke, Yiwei Zhao, Fabio Zinno, Taku Komura ACM SIGGRAPH / TOG
2020	Local Motion Phases for Learning Multi-Contact Character Movements Sebastian Starke, Yiwei Zhao, Taku Komura, Kazi Zaman ACM SIGGRAPH / TOG
2019	Neural State Machine for Character-Scene Interactions Sebastian Starke*, He Zhang*, Taku Komura, Jun Saito, *Joint First Authors ACM SIGGRAPH Asia / TOG
2018	Few-Shot Learning of Homogeneous Human Locomotion Styles Ian Mason, Sebastian Starke , He Zhang, Taku Komura, Jun Saito
2018	Memetic Evolution for Generic Full-Body Inverse Kinematics Sebastian Starke, Norman Hendrich, Jianwei Zhang
2018	Mode-Adaptive Neural Networks for Quadruped Motion Control He Zhang*, Sebastian Starke*, Taku Komura, Jun Saito, *Joint First Authors ACM SIGGRAPH / ТОЗ
2018	Cost Functions to Specify Full-Body Motion and Mutli-Goal Manipulation Tasks Philipp Ruppel, Norman Hendrich, Sebastian Starke, Jianwei Zhang
2017	Evolutionary Multi-Objective Inverse Kinematics on Highly Articulated and Humanoid Robots Sebastian Starke, Norman Hendrich, Dennis Krupke, Jianwei Zhang
2017	A Memetic Evolutionary Algorithm for Real-Time Articulated Kinematic Motion Sebastian Starke, Norman Hendrich, Jianwei Zhang
2017	Prototyping of Immersive HRI Scenarios Dennis Krupke, Sebastian Starke, Lasse Einig, Frank Steinicke, Jianwei Zhang
2017	A Forward Kinematics Data Structure for Efficient Evolutionary Inverse Kinematics Sebastian Starke, Norman Hendrich, Jianwei Zhang

2019	Neural State Machine for Character-Scene Interactions Sebastian Starke*, He Zhang*, Taku Komura, Jun Saito, *Joint First Authors	iGRAPH Asia / TOG
2018	Few-Shot Learning of Homogeneous Human Locomotion Styles Ian Mason, Sebastian Starke , He Zhang, Taku Komura, Jun Saito	Pacific Graphics
2018	Memetic Evolution for Generic Full-Body Inverse Kinematics Sebastian Starke, Norman Hendrich, Jianwei Zhang	IEEE TEVC
2018	Mode-Adaptive Neural Networks for Quadruped Motion Control He Zhang*, Sebastian Starke*, Taku Komura, Jun Saito, *Joint First Authors	M SIGGRAPH / TOG
2018	Cost Functions to Specify Full-Body Motion and Mutli-Goal Manipulation Tasks Philipp Ruppel, Norman Hendrich, Sebastian Starke, Jianwei Zhang	IEEE ICRA
2017	Evolutionary Multi-Objective Inverse Kinematics on Highly Articulated and Humanoid Robots Sebastian Starke, Norman Hendrich, Dennis Krupke, Jianwei Zhang	IEEE IROS
2017	A Memetic Evolutionary Algorithm for Real-Time Articulated Kinematic Motion Sebastian Starke, Norman Hendrich, Jianwei Zhang	IEEE CEC
2017	Prototyping of Immersive HRI Scenarios Dennis Krupke, Sebastian Starke , Lasse Einig, Frank Steinicke, Jianwei Zhang	CLAWAR
2017	A Forward Kinematics Data Structure for Efficient Evolutionary Inverse Kinemat Sebastian Starke, Norman Hendrich, Jianwei Zhang	tics Springer
2016	An Efficient Hybridization of Genetic Algorithms and Particle Swarm Optimizati for Inverse Kinematics Sebastian Starke, Norman Hendrich, Sven Magg, Jianwei Zhang	on IEEE ROBIO
2016	Fast and Robust Detection and Tracking of Multiple Persons on RGB-D Data fusing Spatio-Temporal Information Sebastian Starke, Norman Hendrich, Hannes Bistry, Jianwei Zhang	IEEE MFI

AWARDS

2022	Best Technical Paper Award at ACM SIGGRAPH 2022
2020	Thesis Fast Forward Winner at ACM SIGGRAPH 2020
2020	MACHINA Best Presentation Award at Electronic Arts
2020	O-1 USA Visa (Individuals with Extraordinary Ability or Achievement)
2018	Best Student Paper Award at Pacific Graphics
2017	Highly Commended Paper Award of the Industrial Robot Innovation Award at CLAWAR 2017
2017	Principal's Career Development Ph.D. Scholarship from the University of Edinburgh
2017	Distinction in M.Sc. Informatics from the University of Hamburg
2017	UHH EXPO Winner at the University of Hamburg

PATENTS

P9351-US Neural State Machine Digital Character Animation

SELECTED MEDIA & PRESS RELEASES

Two Minute Papers (Deep Phase)

https://www.youtube.com/watch?v=wAbLsRymXe4

Two Minute Papers (Neural Animation Layering)

https://www.youtube.com/watch?v=t33jvL7ftd4

Two Minute Papers (Local Motion Phase)

https://www.youtube.com/watch?v=pBkFAIUmWu0

Two Minute Papers (Neural State Machine)

https://www.youtube.com/watch?v=cTqVhcrilrE

Two Minute Papers (Quadruped Motion Control)

https://www.youtube.com/watch?v=Mnu1DzFzRWs

AAAS ACM

https://www.eurekalert.org/pub_releases/2019-10/afcm-dnn102919.php

Adobe MAX Keynote

https://max.adobe.com/sessions/max-online/#29631

NVIDIA GTC Keynote

https://www.youtube.com/watch?v=Z2XlNfCtxwl

NVIDIA Developer

https://news.developer.nvidia.com/virtual-character-animation-system-uses-ai-to-generate-more-human-like-movements

Inverse

https://www.inverse.com/innovation/ea-games-motion-capture

CNET

https://www.cnet.com/news/electronic-arts-says-artificial-intelligence-will-make-game-characters-much-more-lifelike

GE Reports

https://www.ge.com/reports/the-5-coolest-things-on-earth-this-week-27

80.lv Articles

https://80.lv/articles/mode-adaptive-neural-networks-for-quadruped-motion-control

Cartoon Brew

https://www.cartoonbrew.com/tools/could-these-be-the-next-high-tech-tools-that-animators-use-daily-158630.html

PAPER REVIEWER

SIGGRAPH, SIGGRAPH Asia, Eurographics, Pacific Graphics, Computer Graphics Forum

INVITED TALKS

GDC 2022, Epic Games, Max Planck Institute, Facebook AI Research, Adobe Research, NVIDIA GPU Technology Conference, McGill Workshop on Computer Animation, Clash of Realities Conference, Hamburg Animation Conference